# Geometry-Aware Framebuffer Level of Detail



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### **Motivation**

- Expensive procedural shading effects – Heavy pixel shader workload
  - Examples
    - Soft shadows
       27fps
    - Ambient Occlusion
       3.2fps
    - Procedural noise texture 120fps





## Motivation

- A method for reducing pixel workload
  - General
  - Lightweight
  - No preprocessing
  - Smoothly adjustable tradeoff between speed/quality



# **Dynamic Resizing**

- Render scene to low-res buffer (1<sup>st</sup> pass), then upsample to target resolution (2<sup>nd</sup> pass). [Montrym97]
  - # of original pixel shader invocation is reduced  $(\propto 1/r^2)$
  - Blurs geometric discontinuities





#### **Geometry-Aware?**



#### **Related Work**

#### • Interleaved sampling [Segovia06, Laine07]



#### Image-based proxy accumulation [Sloan07]





#### **Related Work**

#### • Edge-and-Point render cache [Bala03, Velázquez-Armendáriz06]





#### Overview

- Geometry-Aware Resizing
- Fine-Grained Resizing
- Automatic Framerate Control
- Results and Demo
- Discussions and Conclusion



# **Our Approach**

- Geometry-Aware Resizing
  - Upsample according to geometric similarities between lo-res and hi-res buffers
  - Two-pass technique
    - 1<sup>st</sup> pass: Render geometry with the original pixel shader on low-res buffer, store geometric info (normal & depth) + color
    - 2<sup>nd</sup> pass: Render geometry at full resolution and use geometry-aware kernel to reconstruct the shading from the lo-res buffer





#### **Geometry-Aware Reconstruction**

#### Bilinear



#### Bilateral



#### Weight samples based on geometric similarity







$$c_i^H = \frac{\sum c_j^L f(\hat{x}_i, x_j) g(|n_i^H - n_j^L|, \sigma_n) g(|z_i^H - z_j^L|, \sigma_z)}{\sum f(\hat{x}_i, x_j) g(|n_i^H - n_j^L|, \sigma_n) g(|z_i^H - z_j^L|, \sigma_z)}$$
Color sample *j* from the low-res buffer
Spatial filter: bilinear / biquadratic / bicubic / Gaussian



$$c_i^H = \frac{\sum c_j^L f(\hat{x}_i, x_j) \left[ g(|n_i^H - n_j^L|, \sigma_n) \right] g(|z_i^H - z_j^L|, \sigma_z)}{\sum f(\hat{x}_i, x_j) \left[ g(|n_i^H - n_j^L|, \sigma_n) \right] g(|z_i^H - z_j^L|, \sigma_z)}$$
  
Color sample *j* from the low-res buffer
  
Range filter 1: Gaussian of the *normal* distance



$$c_i^H = \frac{\sum c_j^L f(\hat{x}_i, x_j) g(|n_i^H - n_j^L|, \sigma_n) g(|z_i^H - z_j^L|, \sigma_z)}{\sum f(\hat{x}_i, x_j) g(|n_i^H - n_j^L|, \sigma_n) g(|z_i^H - z_j^L|, \sigma_z)}$$
Color sample *j* from the low-res buffer
Range filter 2: Gaussian of the *depth* distance



 $c_{i}^{H} = \frac{\sum c_{j}^{L} f(\hat{x}_{i}, x_{j}) g(|n_{i}^{H} - n_{j}^{L}|, \mathbf{\sigma}_{n}) g(|z_{i}^{H} - z_{j}^{L}|, \mathbf{\sigma}_{z})}{\sum f(\hat{x}_{i}, x_{j}) g(|n_{i}^{H} - n_{j}^{L}|, \mathbf{\sigma}_{n}) g(|z_{i}^{H} - z_{j}^{L}|, \mathbf{\sigma}_{z})}$ 



Large  $\sigma_z$ , large  $\sigma_n$ 

Small  $\sigma_z$ , large  $\sigma_n$ 



 $c_{i}^{H} = \frac{\sum c_{j}^{L} f(\hat{x}_{i}, x_{j}) g(|n_{i}^{H} - n_{j}^{L}|, \mathbf{\sigma}_{n}) g(|z_{i}^{H} - z_{j}^{L}|, \mathbf{\sigma}_{z})}{\sum f(\hat{x}_{i}, x_{j}) g(|n_{i}^{H} - n_{j}^{L}|, \mathbf{\sigma}_{n}) g(|z_{i}^{H} - z_{j}^{L}|, \mathbf{\sigma}_{z})}$ 



Large  $\sigma_z$ , small  $\sigma_n$ 

Small  $\sigma_z$ , small  $\sigma_n$ 



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# **Fine-Grained Resizing**

- Resize only expensive & spatially smooth computations
- Break up the original shader
  - Expensive & spatially smooth computation:
     1<sup>st</sup> pass (at low-res)
  - Inexpensive / spatially high-freq computation:
     2<sup>nd</sup> pass (at full-res)



#### **Fine-Grained Resizing**





#### **Comparison: Bilinear vs. Bilateral**

#### • Fine-grained resizing + Bilinear upsample?



Geometry-Aware



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## **Automatic Framerate Control**

- Dynamically select resizing factor *r* to maintain a *constant* framerate
- Use a feedback control mechanism
  - Input: previous frame-time
  - Output: r
  - Integral controller





<sup>24</sup> 

## **AFC** implementation

Limit the range of *∆ t*, *∆ r* and *r*Experimentally determine *K*' with the maximum screen coverage



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#### **Results – Car**





#### Results – Car (con't)



#### **Results – Chess**





## Results – Chess (con't)

#### Chess Scene



#### **Results – Dragon**





## Results – Dragon (con't)

#### Dragon Scene



#### **AFC** results

- Experimental data:
  - Over 1000 frames
  - Various outside disturbances
    - View changes
    - Screen coverage changes
    - Shader workload changes



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## Limitations

- Resizing high frequency signal

   Popping and flickering artifacts (aliasing)
- Undersampled fine geometry
  - Missing details around regions with high depth/normal complexities
  - Recompute missing samples in a 3<sup>rd</sup> pass?
- Added geometry processing overhead



## **Practical Advantages**

- Multiple shader / objects
  - Sharing the same resized buffer
  - Sharing the reconstruction pass
  - Allow unified AFC
- Easy to apply

- Mainly an added reconstruction pass



### Conclusion

- A general approach for reducing shading costs
- Respect geometric discontinuities better than conventional resizing
- Allow continuous adjustment of error/performance tradeoff
- Automatic framerate control
- Straightforward to incorporate into existing systems



## **Future Work**

- Multi-resolution resizing
- Automated selection of resized elements
- Resize for super-sample anti-aliasing
- Obtain a Bosnia-Herzegovina visa ③



# **Questions?**



